Computational Self-Awareness: A Paradigm for Adaptive, Resilient Computing Platforms

Nikil D. Dutt

Departments of CS, CogSci, and EECS

University of California, Irvine

dutt@uci.edu

http://www.ics.uci.edu/~dutt

https://duttgroup.ics.uci.edu

Work done jointly with DRG Research Partially Supported by the National Science Foundation



What is Self-Awareness?









Awareness & Adaptation in Biology



[David Gallo: Underwater astonishments, TED]



Awareness vs. Self-Awareness in Biology

Species	Neurons	Synapses	
Nematode	302	10 ³	
Fruit Fly	100,000	107	
Honeybee	960,000	109	MARK NO
Mouse	75,000,000	1011	
Cat	1,000,000,000	10 ¹³	
Human	85,000,000,000	10 ¹⁵	

4

 $Source-http://en.wikipedia.org/wiki/List_of_animals_by_number_of_neurons$



Self-awareness in Sci-Fi 2001, A Space Odyssey (MGM 1968)



- Recognition of mission goals
- Situational Awareness
 - Sense if "something" is wrong or abnormal
- Compensate for sensory impairments
- Deductive reasoning
 - Can see several steps ahead
- Draw conclusions

Copyright © 2019 Dutt Research Group



What is Self-Awareness?

Self-awareness

From Wikipedia, the free encyclopedia

Not to be confused with Self-concept, Self-consciousness, Self-perception, or Self image.

This article has multiple issues. Please help improve [hide] it or discuss these issues on the talk page.

- This article may require cleanup to meet Wikipedia's quality standards. (March 2009)
- This article needs attention from an expert on the

hinest (May 2009)

Self-awareness is the capacity for introspection and the ability to recognize oneself as an individual separate from the environment and other individuals.

1 In philosophy 2 In biology 2.1 Animals

Co

- 2.1 Animais
- 2.2 Evolution
- 2.3 Neurological basis

Conservation



The mirror test is a simple measure of self-awareness.

#6





Variability-induced challenges





Variability-induced challenges



Environment



Variability-induced challenges

Applications: varying compute, memory, communication



Environment





Variability-induced challenges

Applications: varying compute, memory, communication



Environment



Triple Whammy!

node at 1.2V and 0.8V [Dighe10]



• Chips must adapt to Dynamic Performance, Power, Resilience, Security,....

- See Radar chart (Kiviat graph) examples

- Provide Guarantees
- Exploit trade-offs in several dimensions



Ideal Radar Chart?







Copyright © 2019 Dutt Research Group





Copyright © 2019 Dutt Research Group





Copyright © 2019 Dutt Research Group







What we want: QoS Combination



QoS Combination



Energy/Power Driven



Security Driven



Reliability Driven

Performance Driven

Copyright © 2019 Dutt Research Group





Outline

- Computational Self-Awareness
- Exemplar: Cyber-Physical Systems-on-Chip (CPSoC)
- Managing Self-Awareness and Autonomy
- Wrap-up



Outline

- Computational Self-Awareness
- Exemplar: Cyber-Physical Systems-on-Chip (CPSoC)
- Managing Self-Awareness and Autonomy
- Wrap-up





What's a Cyber-Physical System-on-Chip (CPSoC)?

- Cyber-Physical System
 - Cyber = Embedded Systems and IT
 - HW, SW, Networking/Communication
 - Physical = Environment
 - Sensing, Actuation, Control
- System-on-Chip (SoC):
 - Many-core computing platform: processors, memories, interconnects
- Cyber-Physical System-on-Chip (CPSoC):
 - Sensor-actuator rich adaptive SoC platform
 - Self-awareness
 - Predictive modeling and learning



Cyber-Physical System-on-Chip (CPSoC)

• Cross-Layer Virtual and Physical Sensing & Actuation

- Sensor fusion and Actuation
 - Combine hardware and software sensors

• Self-Awareness and Adaptation

- Combines *Simple* and *Self-Aware* adaptions
- A reflective (**Observe-Decide-Adapt**) architecture to achieve closed loop system control
- Predictive Modeling & Learning
 - Dynamic characterization of platform variability across multiple levels of the system stack.





Cyber-Physical System-on-Chip (CPSoC)

- Cross-Layer Virtual and Physical Sensing & Actuation
 - Sensor fusion and Actuation
 - Combine hardware and software sensors
- Self-Awareness and Adaptation
 - Combines *Simple* and *Self-Aware* adaptions
 - A reflexive (**Observe-Decide-Adapt**) architecture to achieve closed loop system control
- Predictive Modeling & Learning
 - Dynamic characterization of platform variability across multiple levels of the system stack.





Cross-Layer Physical/Virtual Sensing & Actuation



Examples of Virtual Sensors and Actuators Across Layers of CPSoC

Layers	Virtual/Physical Sensors	Virtual/Physical Actuators
Application	Execution Time, Workload Power, Energy,	Loop perforation Algorithmic Choice
Operating System	System Utilization Peripheral States	Task Allocation, Scheduling, Migration, Duty Cycling
Network/Bus Communication	Bandwidth; Packet/Flit status; Channel Status, Congestion, Latency	Adaptive Routing Dynamic Bandwidth Allocation Ch. no and direction
Hardware Architecture	Cache misses, Miss rate; access rate; IPC, Throughput, ILP/MLP, Core asymmetry	Cache Sizing; Reconfiguration, Resource Provision Static/Dynamic Redundancy
Circuit/Device	Circuit Delay, Aging, leakage Temperature, oxide breakdown	DVFS, DFS, DVS ABB, Clock and Power-gating

Cyber-Physical System-on-Chip (CPSoC)

- Cross-Layer Virtual and Physical Sensing & Actuation
 - Sensor fusion and Actuation
 - Combine hardware and software sensors
- Self-Awareness and Adaptation
 - Combines *Simple* and *Self-Aware* adaptions
 - A reflective (**Observe-Decide-Adapt**) architecture to achieve closed loop system control
- Predictive Modeling & Learning
 - Dynamic characterization of platform, application, and environment variability across multiple system levels



What are Self-Aware Chips?

- Self-Aware chips
 - *Construct model* of behaviors and environment using sensor data
 - Achieve *self-awareness* through on-chip sensors and monitors
 - Experience phenomena
 - Aware of state and behavior
 - The ability to *introspect*
 - Adapt behavior based on model of external and internal environment



Reflex vs Reflect

Reflexive, Reactive



- Actions driven solely on external feedback
 - E.g., our autonomic nervous systems



Reflex vs Reflect

Reflexive, Reactive

Reflection, Introspection





- Actions driven solely on external feedback •
 - E.g., our autonomic nervous systems
- **Consider past and future outcomes** •
 - E.g., planning, strategies, policies, ...





Towards Self-Aware Chips: What we do now

Reflexive, Reactive







Towards Self-aware chips

Beyond simple reactive models





Towards Self-aware chips

Beyond simple reactive models





Today: "Reactive" Resource Management

• Dynamic Voltage/Frequency scaling (DVFS)



• Observe-Decide-Adapt approaches





Reactive vs Refle**CT**ive Resource Management



- *Reactive ODA*: decisions taken based on •
 - **past** observations (purely reflexive) OR
 - predictions made from **past** observations •





Reactive vs Refle**CT**ive Resource Management



- predictions made from **past** observations
- **RefleCTive approach**: considers **future** events that could happen in the next iteration of the ODA loop



Adaptive Resource Management

- Use concept of **reflection**
 - Reflection: change your actions based on both external feedback and introspection (i.e., selfassessment)



Adaptive Resource Management

- Use concept of reflection
 - Reflection: change your actions based on both external feedback and introspection (i.e., self-assessment)
- Reflective resource management combines:
 - Current system state assessed from sensing information (e.g., readings from performance counters, power sensors, etc.)
 - Models to predict the behavior of other system components before performing an action





MARS: Our coordination approach

- Coordination though **reflective** resource management
 - MARS: Middleware for Adaptive Reflective Systems





Do we have room for reflection ?

• Systems actuations happen at different timescales



- Some actuations happen quickly with little room for reasoning
- Other actuations can occur on larger timescales
 - Task mapping, Wear-leveling (for aging)....





MARS middleware for reflective resource management







MARS middleware for reflective resource management







MARS middleware for reflective resource management





MARS: Middleware for Adaptive Reflective Computer Systems

- Framework and tools for developing reflective resource/power management policies
 - Use models to predict system behavior
 - Enable easy adaptation to runtime changes
 - Case studies show promise

MARS framework is open source!



https://duttgroup.ics.uci.edu/projects/self-aware-adaptive-computing/mars/ https://github.com/duttresearchgroup/MARS





Outline

- Computational Self-Awareness
- Exemplar:Cyber-Physical Systems-on-Chip (CPSoC)
- Managing Self-Awareness and Autonomy

• Wrap-up



Goals and Autonomy

Goal



- Single, straightforward objective
 - **E.g.**, hit the pin

٠

Copyright © 2019 Dutt Research Group





Goals and Autonomy

Goal



- Single, straightforward objective
 - **E.g.**, hit the pin

.

Model Imperfection





- What happens when we introduce unpredictability?
 - E.g., balls with different sizes, shapes weights; uneven or damaged surfaces



Goals and Autonomy Supervision



- Constrain behavior so we are always headed toward the goal
 - **E.g.**, bumpers



Goals and Autonomy Supervision



- Constrain behavior so we are always headed toward the goal
 - E.g., bumpers
- **Bonus:** what about when we have more complex or multiple goals?





SPECTR: Our Supervisory Approach

- Autonomy and robustness through supervisory control
- Case Study (ASPLOS 2018 Paper)*

Supervisor bounds behavior of controllers, manages goal



Low-level controllers satisfy objective

*Rahmani, A. M., Donyanavard, B., Mück, T., Moazzemi, K., Jantsch, A., Mutlu, O., & Dutt, N., SPECTR: Formal Supervisory Control and Coordination for Many-core Systems Resource Management. ASPLOS '18

Copyright © 2019 Dutt Research Group





Self-* Computing: Related Efforts

- Self-test, Self-diagnosis, Self-Repair for chips and computing platforms (several decades)
- Reflective SW and Autonomic Computing (IBM) (circa 2003)
- ODA-based feedback control strategies for adaptive computing (circa 2011)
 - SEEC (MIT/ Milano)
 - Organic/Invasive Computing Germany)
 - Software centric/focused adaptation of computing platform resources

• Missing pieces:

- Cross-layer sensing/actuation
- Self-modeling and introspection
- Control/coordination of emergent behaviors





IPF: Self-Aware / Self-Organizing Information Processing Factory



 Scalability of control through higher sub-system autonomy while operating within a corridor of guaranteed objectives and operation parameters









Objectives of a Self-Aware Information Processing Factory

• Holistic, hierarchically structured platform control

- As modular and decentralized as possible, …
- ... as much centralized as necessary
- Scalability and dynamic elasticity
 - react to short/long term workload fluctuations
 - platform uncertainties

Orthogonal functional and control complexity

- Inspired by self-organization and emergent phenomena in nature
 - Self-awareness: introspection + ubiquitous sensing of platform and environment
 - Self-organization: local actions

Predictive guarantees for critical tasks / functions

Long term planning and logistics



Self-Aware / Self-Organizing Information Processing Factory







Comparing Use Case Requirements

Automated Driving

Safety, lifetime and resilience dominated
Foreseeable future challenges with power, security and performance

Mobile Devices

Performance / W, size, security and cost are main challenges
Safety in context of medical applications expected to rise



Trend: System evolution and convergence (SmartPhones as integrated devices in future cars) will lead to requirements convergence



Outline

- Computational Self-Awareness
- Exemplar: Cyber-Physical Systems-on-Chip (CPSoC)
- Managing Self-Awareness and Autonomy
- Wrap-up



Key Take-Away 1: Cross-Layer Physical/Virtual Sensing & Actuation



From today's chips

Reflexive, **Reactive**





Self-monitoring and simple adaptation





Key Take-Away 2: Towards on-chip self-awareness



Self-monitoring and **Self-modeling**

Copyright © 2019 Dutt Research Group

https://duttgroup.ics.uci.edu

[Sarma14, CODES+ISSS14]

#60



Key Take-Away 3: Supervisory Control & Coordination





VOLUME 34 NUMBER 6





Special Issue on Self-Awareness in Systems on Chip 2017

· Self-Awareness in Systems on Chip—A Survey ealth Management for Self-Aware SoCs Based on IEEE 1687 Infrastructure KOCL: Powe careness for Arbitrary FPGA-SoC-Accelerated OpenClreions vegi-inreshold Processors

· A Self-Aware Architecture for r vi

· Self-Adaptive Timing Repair



Contents

November/December 2017 Volume 34 Number 6

Special Issue

Copublished by the IEEE Council

on Electronic Design Automation

the IEEE Circuits and Systems

Society the IEEE Solid-State

Circuits Society, and the Test

Technology Technical Council



Systems on Chip—A Survey

Axel Jantsch, Nikil Dutt, and Amir M. Rahmani

ealth Management for Self-Aware SoCs Based on IEEE 1687 Infrastructure Konstantin Shibin, Sergei Devadze, Artur Jutman, Martin Grabmann, and Robin Pricken

KOCL: Power Self-Awareness for Arbitrary FPGA-SoC-Accelerated **OpenCL** Applications James J. Davis, Joshua M. Levine,

Edward A. Stott, Eddie Hung, Peter Y. K. Cheung, and George A. Constantinides

Self-Aware Architecture for PVT Compensation and Power Nap in **Near-Threshold Processors**

> Davide Rossi, Igor Loi, Antonio Pullini, Christoph Müller, Andreas Burg, Francesco Conti, Luca Benini, and Philippe Flatresse



36

Hans Giesen, Raphael Rubin, Benjamin Gojman, and André DeHon

Survey Paper



General Interest

84

94



daptive ECC for Tailored AProtection of Nanoscale Memory

Dongyeob Shin, Jongsun Park, Jangwon Park, Somnath Paul, and Swarup Bhunia

Tajana Rosing, Abbas Rahimi, and Ian M. Rabaev

ISSN: 2168-2356



SelPhyS 2019 and ACM TCPS Special Issue





Ongoing Challenges

- Self-trained models
 - Add feedback for error correction
 - Challenging for models that are non-linear and/or based on heuristics
- Machine learning
 - Replacement for analytical/heuristic-based models ?
 - Unsupervised machine learning to mine sensing data and find patterns for optimizing policies or creating new ones
- Policy supervisors
 - Provide formal or stronger guarantees





Acknowledgements

- Dutt Research Group (IPF Team)
 - Bryan Donyanavard, Tiago Mück, Amir Rahmani, Santanu Sarma, Kasra Moazzemi, Biswadip Maity, Saehanseul Yi, Caio Batista de Melo, Kenneth Stewart
- Collaborating Faculty:
 - UCI: Fadi Kurdahi
 - Germany: TUM: Prof. Andreas Herkersdorf, TUB: Prof. Rolf Ernst
 - Austria: TU Wien: Prof. Axel Jantsch
- NSF/DFG Information Processing Factory (IPF) project



Questions?



Dutt Research Group: http://duttgroup.ics.uci.edu/

Copyright © 2019 Dutt Research Group



