





Introduction on Cyber Physical Systems Francesca Palumbo

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CPS Summer School – From concepts to implementation Porto Conte Ricerche, Alghero (IT) 25–29 September 2017

Let's go straight to the point!

https://www.youtube.com/watch?v=U7y1wiYqHDc



Numbers: opportunity or issue?







20 MWh/year 1,800 kg oil



> 1 billion smartphones
8.4 billion connected things in 2017 (+31% wrt 2016)
20.4 billion by 2020
http://www.gartner.com/newsroom/id/3598917
Francesca Palumbo, UNISS

Computing Evolution

UBIQUITUOUS COMPUTING & INFORMATION PERVASIVE COMPUTING DISAPPEARING COMPUTERS EMBEDDED EVERYWHERE



POST PC ERA + PHYSICAL ENTANGLEMENT



CPS ERA

Formal Definitions

CPS are *smart systems* that include *engineered interacting networks of physical and computational components*. National Institute of Standard and Technology (NIST), US. CPS Public Working Group

A cyber-physical system (CPS) is an orchestration of computers and physical systems. Embedded computers monitor and control physical processes, usually with feedback loops, where physical processes affect computations and vice versa. Edward A. Lee

University of Berkeley



Key Ingredients



Key Ingredients



Yet Another Definition

CPS are *engineered systems* that are built from, and depend upon, the *seamless integration of computational algorithms and physical components*.

Advances in CPS will enable *capability, adaptability, scalability, resiliency ...* that will far exceed the simple embedded systems of today.

CPS technology will *transform the way people interact with engineered systems* -- just as the Internet has transformed the way people interact with information.



National Science Foundation (NSF), Cyber-Physical Systems Group

Embedded Systems and CPS

Embedded Systems: dedicated computing elements, everyday more complex, that brought the integration of information into products.



CPS Concept Map



DEDICATED: towards a certain application. Knowledge of behaviours may

- improve resource minimization and robustness
- require optimized user interfaces

HYBRID: composed of different

- views (cyber, physical and communication),
- components (hardware and software, analog/digital devices),
- interfaces (e.g. humans, networks).

REACTIVE:

by definition reactive systems are characterized by continuous interactions with the environment where they operate, and execute at a pace that may be determined by the environment.

DYNAMIC: CPS are supposed to adapt to

- changes in the environment;
- runtime variation of the requirements;
- fluctuations in the amount of exchanged and sensed data.

Real-time situation awareness, dynamic and reactive behaviours have application in...

Smart-Health:

distributed healthcare assistance to improve quality of life and active and healthy ageing.

Smart-Society:

increased building efficiency and comfort (i.e. lightning/air quality management).

Smart-Transportation: autonomous vehicle, improved driver assistance and care.

| | Safety | Security | Certif. | Distrib. | IMH | Seamles s | MPSoC | Energy |
|------------|--------|----------|---------|----------|-----|--------------|-------|--------|
| Automotive | X | х | х | x | x | х | Х | |
| Aerospace | X | х | х | x | x | | Х | x |
| Healthcare | X | х | х | x | x | x | Х | x |
| Consumer | | | | | X | х | X | |

Cognitive CPSTALKING ABOUT TRENDS and APPLICATIONSMichael Masin (IBM, IL) and Paolo Meloni (University of Cagliari, IT)

The (Smart) Cyber-Physical Revolution: From Theory to Practice Danilo Pau (ST Microelectronics, IT)

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| Consumer | | | | | x | x | X | |

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| Aerospace | X | X | X | x | х | | X | x |
| Healthcare | X | Х | X | x | х | x | X | x |
| Consumer | | | | | Х | x | Х | |

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| Automotive | Х | Х | x | X | Х | х | X | |
| Aerospace | X | Х | х | Х | х | | X | х |
| Healthcare | X | Х | x | x | х | x | X | x |
| Consumer | | | | | X | x | X | |

ISSUE # 1 Modelling CPS

Separation of concerns, normally adopted to simplify complexity and heterogeneity, leads to miss important cross-domain interactions.

We need to find proper way of modelling CPS.

The Kopetz Principle

Prof. Dr. Hermann Kopetz

Many (predictive) properties that we assert about systems (determinism, timeliness, reliability, safety) are in fact not properties of an *implemented* system, but rather properties of a *model* of the system.

We can make definitive statements about *models*, from which we can *infer* properties of system realizations. The validity of this inference depends on *model fidelity*, which is always approximate.

Edward Lee,

"Cyber-Physical Systems A Rehash or A New Intellectual Challenge?", DAC 2013

The Synchronous Digital Logic Example

- The model has exactly one behavior.
- Unambiguously definition of the "correct" behavior of the thing being modeled.

Models are EXTREMELY POWERFUL engineering abstractions
 The real problem is that NON DETERMINISM arises as soon as you cross the border.

• Why does NON-DETERMINISM arise?

- Lack of temporal semantics;
- The real world is full of uncertainties.


```
if x>100 {
   //this code execute
   if (x==0) {
        // should NOT execute
        printf("ERROR!")
        }
}
```


- The REAL BEHAVIOUR comes out when you put together the model with the physical realization of the system.
- You need to guarantee ROBUSTNESS!

CPS Modelling Nightmare

- Modelling the dynamics and the interaction among the heterogenous and divers view of a CPS is certainly an OPEN ISSUE.
- > Dynamic and reactive behaviours have to be guaranteed.

TALKING ABOUT MODELLING AND PROPERTIES

Let's get Physical: Adding Physical Dimensions to Cyber Systems Alberto Sangiovanni-Vincentelli (University of Berkeley, US)

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ISSUE # 2 Heterogeneity and Flexibility in CPS

CPS are requested to be *reactive* and *dynamic* to adapt, prospectively autonomously,

- > to rapid changes in the environment and in the system itself;
- to satisfy multiple concurring and, potentially, competing requirements.

The intrinsic dynamic and reactive nature of CPS requires flexibility.

- Self-reconfiguration and adaptation have been acknowledged as key features for CPS operators:
 - in mixed-critical environments;
 - to handle faults.

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TALKING ABOUT HETEROGENEITY AND ADAPTIVITY

Robust Heterogeneous Computing for CPS Muhammad Shafique (TU Wien, AU)

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ISSUE # 3 Model-based Engineering and Design Tools

Despite their big promise, model-based frameworks are not as popular as it could be expected.

Modeling, maintenance, and interoperability overhead are not addressed in a satisfactory way.

Classical V-model

Separate design, implementation and validation phases

- long time to market
- complex HW/SW tuning phase
- Collection of partially integrated toolchains

State-of-the-Art Tools

| | Μ | 0 | D | G | S |
|---|---|---|---|---|---|
| Simulink/Stateflow | N | | X | X | X |
| (www.mathworks.nl/products/simulink) | | | | | |
| Modelica/Dymola (<u>www.3ds.com</u>) | x | | x | | x |
| SysML (www.sysml.org) | x | | x | | |
| MARTE (www.omgmarte.org) | x | | x | | |
| SCADE (www.esterel- | V | | V | V | V |
| technologies.com/products/scade-suite/) | | | | | |
| gPROMS (www.psenterprise.com/gproms.html) | x | x | | | X |

M=Modelling, O=Optimization, D=Design, G= code Generation, S=Simulation

The Tool Integration Nightmare

Go for semantic integration rather than for tools combination!

Semantic-oriented Tool Integration

- Do not put tools toghether! Combine the modelling paradigms.
 TALKING ABOUT TOOLS
- A Contract-Based Design Methodology for Cyber Physical Systems Alberto Sangiovanni-Vincentelli (University of Berkley, US) HW/SW Cyber-System modelling tools Karol Desnos (INSA-Rennes, FR) and Julio De Oliveira Filho (TNO, NL) High Level Synthesis methods Jocelyn Serot (Institut Pascal, FR) From high-level specification down to hardware Francesca Palumbo (University of Sassari, IT) and Christian Pilato (ALaRI, CH)

HANDS ON DAY The CERBERO Project tools

THE RECEPY OF SUCCESS ... be open minded!

Blind Man and the Elephant Problem

Humans tens to project their partial experiences as the whole truth, ignoring other people's partial experiences.

Integral ApproachScience!

- Huge mistake in CPS design
 - heterogeneity;
 - multi-vendor, multi-physics and multi-modelling;
 - wide variety of requirements and constraints.

You need to be willing

- to change your point of view;
- to play with new tools and experimentations;
- to combine several different components and domains together.

Integral Approach ... Funding Programmes!

USEFUL READS

Something for you to read ...

- The Past, Present and Future of Cyber-Physical Systems: A Focus on Models,
 E. A. Lee https://www.ncbi.nlm.nih.gov/pmc/articles/PMC4435108/
- Framework for cyber-physical systems, release 1.0 NIST 2016 – https://pages.nist.gov/cpspwg/
- Metronomy: A function-architecture co-simulation framework for timing verification of cyber-physical systems,

L. Guo, Q. Zhu, P. Nuzzo, R. Passerone, A. L. Sangiovanni-Vincentelli and E. A. Lee CODES+ISSS 2014

> Design tool chain for cyber-physical systems: lessons learned,

J. Sztipanovits, T. Bapty, S. Neema, X. D. Koutsoukos, and E. K. Jackson DAC, 2015

Modeling Cyber-Physical Systems,

P. Derler, E. A. Lee, and A. L. Sangiovanni-Vincentelli Proceedings of the IEEE, 2011

- Is a Unified Methodology for System-Level Design Possible?,
 - A. L. Sangiovanni-Vincentelli

IEEE Design & Test of Computers, 2008 Francesca Palumbo, UNISS